



RETRACTABLE THRUSTERS

BTR 140 30 - 140 40 **BTR** 185 65 - 185 85 - 185 105 **BTR** 250 120 - 250 140 - 250 240 **BTR** 300 250 - 300 270 - 300 300



***EN -** INSTALLATION AND USER'S MANUAL

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1.0 - Technical Data

MODE	LS	BTR 140	-30	BTR 140-40			
No. of	Propellers	Single					
Tunnel	Ø	140mm (5″ 33		3/64)			
Motor	oower	1.5 kV	/	2.2 kW			
Voltage	,	12 V		12 V			
Fuse		150A CNL	DIN	225A CNL DIN			
Thrust		30 kgf (66	5 lb)	40 Kgf (88.2 lb)			
Weight		26.4 kg (58	3.2 lb)	27.3 kg (60.2 lb)			
1ded 5- (* *)	L<5m	35mm² (AV	VG 2)	50mm ² (AWG 1)			
mer cross	5.1 < L < 10m	50mm² (AV	VG 1)	70mm ² (AWG 2/0))		
Recommended cable cross- section (*) (* *)	10.1 < L < 20m	70mm² (AW	'G 2/0)	95mm² (AWG 3/0))		
MODE	LS	BTR 1	85-65	BTR 1	85-85	BTR 18	5-105
No. of	Propellers			2 counter rotating	g (technopolyme	r)	
Tunnel	Ø			185mm (7″ 9/32) in		
Motor	oower	3.3	kW	4.3	kW		
Voltage	2	12 V	24 V	12 V	24 V	12 V	24 V
Fuse		275 A CNL DIN	175 A CNL DIN	400 A CNL DIN	275 A CNL DIN	400 A CNL DIN	275 A CNL DIN
Thrust 65 kgf (143.3 lb)		85 kgf (1	gf (187.4 lb) 105 kgf (231.5 lb)		31.5 lb)		
Weight		37.6 kg (82.9 lb)	37.8 kg (83.3 lb) 37.9 kg (83.5 lb)	40.5 Kg (89.3 lb)	46.4 kg (102.3 lb)	44 kg (97.0 lb)
Recommended cable cross- section (*) (**)	L<5m	70mm ² (AWG 2/0)	50mm ² (AWG 1)	2 x 50mm ² (2 x AWG 1)	70 mm ² (AWG 2/0)	2 x 70mm ² (2 x AWG 2/0)	70mm ² (AWG 2/0)
ecomm able cro	5.1 < L < 10m	2 x 50 mm ² (2 x AWG 1)	70mm ² (AWG 2/0)	2 x 70mm ² (2 x AWG 2/0)	2 x 50mm ² (2 x AWG 1)	2 x 95mm ² (2 x AWG 3/0)	2 x 50 mm ² (2 x AWG 1)
888	10.1 < L < 20m	2 x 70 mm ² (2 x AWG 2/0)	95mm² (AWG 3/0)	2 x 95mm ² (2 x AWG 3/0)	2 x 70mm ² (2 x AWG 2/0)	2 x 120mm ² (2 x AWG 4/0)	2 x 70mm ² (2 x AWG 2/0)
MODE	LS	BTR 250-120	BTR 250-140	BTR 250-240	BTR 300-250	BTR 300-270	BTR 300-300
No. of	Propellers			2 counter rotat	ing (technopolyn	ner)	
Tunnel	Tunnel Ø 250 mm (9" 27/32)		2) in		300 mm (11" 13/1	6) in	
Motor	oower	6.5 kW	8 kW	10 kW	10 kW	12 kW	15 kW
Voltage	2			24 V			48 V
Fuse		275 A CNL DIN	400 A CNL DIN	400 A CNL DIN	400A CNL DIN	500 A CNL DIN	500 A CNL DIN
Thrust		120 kgf (264 lb)	140 kgf (308 lb)	240 kgf (529 lb)	250 kgf (551 lb) 270 kgf (595 lb)) 300 kgf (660 lb)
Weight		82.1 kg	(181 lb)	97 kg (213.8 lb)	97 kg (214lb)	106 kg (234 lb)	113 kg (249 lb)
L<5m			nm² 6 2/0)	2 x 50mm ² (2 x AWG 1)	70mm ² (AWG 2/0)	2 x 95mm ² (2 x AWG 3/0)	95mm ² (AWG 3/0)
Recommended cable cross- section (*) (**)	5.1 < L < 10m		0mm² .WG 1)	2 x 70mm ² (2 x AWG 2/0)	2 x 50mm ² (2 x AWG 1)	2 x 95mm ² (2 x AWG 3/0)	2 x 70 mm ² (2 x AWG 2/0)
	10.1 < L < 20m		0mm² VG 2/0)	2 x 95mm ² (2 x AWG 3/0)	2 x 95 mm ² (2 x AWG 3/0)	2 x 120mm ² (2 x AWG 4/0)	2 x 95mm ² (2 x AWG 3/0)

(*) L = positive cable + negative cable

(**) Other solutions are allowed, provided that they are supported by the connecting terminals. Respect minimum area indicated.

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2.0 - Standard supply and material included in the package

- Retractable thruster
- O-ring
- Hinge
- Hatch bracket
- Steel wire rope
- Installation and user's manual
- Warranty conditions

2.1 - Tools required for installation

BTR 140	 Phillips screwdriver Wire cutters Drill and drill bit Ø 8.5 mm Allen wrench: 2.5 mm Fork wrench: 8 mm and 13 mm
BTR 185	 Phillips screwdriver Wire cutters Drill and drill bit Ø 8.5 mm Allen wrench: 2.5 mm Fork wrench: 8 mm and 13 mm
BTR 250	 Phillips screwdriver Wire cutters Drill and drill bit Ø 8.5 mm Allen wrench: 2.5 mm and 10 mm Fork wrench: 8 mm, 13 mm and 17 mm
BTR 300	 Phillips screwdriver Wire cutters Drill and drill bit Ø 8.5 mm Allen wrench: 2.5 mm and 10 mm

• Fork wrench: 8 mm, 13 mm and 17 mm

2.2 - Recommended Quick® accessories not included

- TCD thruster controls
- TSC integrated line switch control
- TMS line switch
- PSS parallel battery switch
- TFH Fuse holder



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BEFORE USING THE PRODUCT, PLEASE READ THIS USER'S MANUAL CAREFULLY. IF IN DOUBT, PLEASE CONSULT YOUR QUICK® DEALER.

3.0 - Important notes

This manual features Warning and/or Caution symbols that are important for safety. Please follow the instructions provided.



Warning symbol indicating dangerous situations.



Caution symbol to prevent direct or indirect damage to the product.

This manual provides boat manufacturers and nautical equipment installers with instructions on how to assemble the specified Quick® product and operate it correctly.





3.1 - Precautions



Quick® thrusters have been designed and constructed only for nautical use.

- Do not use these products for any other type of operation.
- Quick[®] shall not be held liable for direct or indirect damage caused by improper use of the product.
- The product is not designed to support loads generated in particular atmospheric conditions (storms).
- Operate the product from a position where it is possible to supervise the work area.
- Always deactivate the thruster when not being used.
- For improved safety, we recommend installing at least two controls to operate the product in case one is damaged.
- The installer shall bear full responsibility for any problems caused by defective installation of the tunnel.
- This equipment is not intended for use by people (including children) with reduced physical, sensory or mental capabilities.
- Do not install the electric motor near easily inflammable objects.

3.2 - Precautions for the installer



CARRY OUT THE INSTALLATION IN GOOD LIGHTING CONDITIONS.

It is advisable to wear suitable clothing and personal protective equipment (PPE).

The product is not suitable for installation in potentially explosive environments and/or atmospheres. Installation and subsequent inspection or repair work must only be carried out by qualified personnel.



CARRY OUT INSTALLATION/MAINTENANCE WORK MAKING SURE THAT THE PRODUCT IS DISCONNECTED FROM THE ELECTRICAL SYSTEM.

Quick[®] accepts no responsibility for inadequate connection of users to the electrical system and inadequate safety of the electrical system.

3.3 - Installation requirements

We recommend you entrust preparation and positioning of the tunnel in the hull to a skilled professional.

These are generic instructions and do not give details of the preparatory operations for installing the thruster, since this is the competence of the boatyard. The installer shall bear full responsibility for any problems caused by defective installation.

Although all the components and mechanical moving parts are of high quality, the correct installation of the driving unit is an essential basis for the safe and effective use of the boat as well as the driving unit itself.

The installation of such a unit is an operation that requires experience as well as technical skills. It is recommended that the installation be carried out by competent personnel and that the manufacturer or naval architects be consulted to fully assess the scope of the work.

The Quick® retractable thruster has two separate movements.

The main movement, relative to the driving unit, is of the tilting type. The hinges on which the movement takes place are designed for assembly high resistance and are located on the plane of the flat flanging that links the pre-assembled structure to the support integral to the hull.

The secondary movement relates to the closing movement of the thru-hull from which the tunnel comes out. This tilting movement is performed around the hinge that has been designed and manufactured for an interference-free opening of the hatch (if installed as instructed).

Electric motor, gearbox, linkages and all other components are supplied by Quick® already assembled on the GRP support structure and do not require adjustments, adaptations or sealing, unless specified in this manual.

The Quick® retractable thruster is sold separately from the counter flange which can be supplied in different materials based on the different type of hulls. Quick® can provide stainless steel, aluminium alloy or GRP supports, which are essential for a fast, sturdy and precise installation.

For fibreglass hulls, the support must be laminated in the hull in compliance with current regulations on joints. The driving unit distributes mechanical stresses to the hull through the counter flange. The strength of the joint will be determined by overlapping laminations, made in a "workmanlike" way.

For aluminium alloy hulls or stainless steel hulls, the support needs to be welded to the hull.

If well done, the installation of a box structure such as that of the support can give greater strength to the hull. Refer to the manufacturer, naval architects and/or specialised companies to evaluate additional works such as beams and supporting structures near the position of the retractable driving unit.



4.0 - Thrusters position



• To avoid cavitation in the thruster, the tunnel must be positioned as low as possible.



• To avoid damage, position the retractable thruster so that the hatch is not affected by the thruster driving cone of the boat (examples 1 and 2), in both directions of travel.



• The longer the lengths L1 and L2, the greater the thrust generated around the barycentre.



4.1 - Counter flange installation

• Protect the seal seat with gummed paper tape to prevent it from getting dirty, until the retractable thruster is installed (Fig. 1A).



• Shape the central parts of the 4 indicated sides of the counter flange by adapting them to the curve of the hull (fig. 1C).

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• Place the appropriately cut counter flange and check that the four sides adhere to the hull, if this is not the case, adapt it until it rests and adheres to the hull in the position where it is meant to be fixed.



WARNING: take into account the minimum dimensions for the final placement of the hinge (see fig. 13, page 12).





• Mark the inner perimeter of the counter flange on the hull with a marker (fig. 2).





• Remove the counter flange and mark the cutting area: (fig.3)

	Ø140	Ø185	Ø250	Ø300
Α	320mm	350mm	480mm	604mm
В	100mm	95mm	150mm	110mm
С	200mm	280mm	310mm	440mm
D	0mm	0mm	20mm	0mm

Fig.4



• Make the hull opening by cutting along the line of the marked cutting area (fig. 4).

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• Align the counter flange with the opening of the hull and **check that the 4 heights indicated in fig.B page 9** are correct. Apply resin to the counter flange or weld it, in the case of aluminium or steel, according to the techniques identified as the most suitable for the type of hull construction (fig. 5).



• On the entire perimeter of the hull opening, make a sturdy stop for closing the hatch (fig. 6).

4.2 - Construction and installation of the closing hatch

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WARNING: take special care to avoid interference between the cover and the hull opening. Too precise contacts will cause damage to the entire movement system (fig.7).



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• Make the closing hatch maintaining a clearance on all sides from 3 to 5 mm, paying particular attention to the hinge side, making the internal walls inclined at 45° so that they do not interfere with the hull opening (fig.7 and 8).

- To achieve the correct opening of the hinge, the hull and hatch surfaces must be on the same level (fig. 9).
- The thickness of the hull must be max. 35mm (Ø185) 50mm (Ø250) (fig. 8).
- Correctly adjust the angle bracket on the hull (fig. 10A and 10B ref. A).
- Fix the angle bracket with structural glue (fig. 10B ref. B1 B2).
- Choose whether to fix the angle bracket to the hull with 3 M8 screws or by applying resin (fig. 10B ref. C1 C2).



Fig.11



- Temporarily fix the hatch in its seat.
- Screw the hinge onto the angle bracket with the central screw only (fig. 11).
- Place the hinge and hatch bracket in the correct positions.
- Mark all the fixing points (fig. 12), remove the hinge and the hatch bracket and drill with a Ø 8.5mm drill bit.

• Fix the hinge and the hatch bracket in the positions made using stainless steel screws suitable for the application.

• Adjust the central hinge screw (fig. 11) and position it correctly so that the hatch opens unhindered.





• Drill the angle bracket and also secure the other two M8 screws (fig. 13) firmly.

4.3 - Retractable thruster installation



• Remove the previously applied adhesive protectors from the counter flange.

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Verify that the O-ring seat is well cleaned and has not been damaged during installation.
Position the O-ring correctly on the counter flange (ref. 14A), assemble the retractable thruster (fig.14), spread marine grease on the bolt threads (ref. 14B) and fix securely with the supplied screws.

The counter flange screws should be tightened to 15Nm, tightening little by little in a cross pattern as in the example in figure 15.

WARNING: after about a week from installation, check the correct tightening of the screws to compensate for any settling of the O-ring.



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4.4 - Motor installation

Fig. 15

- Grease the drive shaft and make sure the key is properly positioned.
- Insert the motor and fix it with the suitably greased 4 screws and 4 growers supplied (fig. 15A).
- Connect the fastons respecting the polarities (fig. 15B).



4.5 - Check and mechanical adjustment of the system

Follow the sequence below to check hatch opening:

Fig. 16

- The retractable thruster should not be powered.
- Remove the ring and the pin (ref. A).

• Release the actuator from the lever (ref. B), make sure the system can be opened and closed smoothly without mechanical hindrance.



Warning: when manually releasing the actuator the thruster with its weight comes out completely, hence make sure that no one is within its operating range.

4.6 - Installing the cable in the hatch



• Insert one end of the cable into the hatch bracket (ref. A).



• Hook the ends of the cable to the two springs (already positioned on the tilting body) (ref. C).



Fig. 16

Α

В

• Run the cable under the guide attached to the tunnel (ref. B)



• Final installation of the cable in the hatch (ref. D).









Make sure the system can be closed and opened again smoothly without mechanical hindrance.

4.7 - Adjustment procedure

WARNING: the following procedure must be performed by qualified personnel.

WARNING: presence of moving mechanical parts. Take special care when operating on a powered retractable thruster.

- Make sure that all electrical connections have been made correctly.
- Remove the cover from the RTC R1 board housing (fig.18).
- Switch to "manual mode" to adjust the limit switches.

• Press and hold down both the UP and DOWN buttons on the board (fig. 19) to power the RTC R1 electronic board until the POWER LED (green) flashes rapidly (fig. 19 ref. A). Then release both buttons.

• Now it is possible to control the actuator electrically with the UP and DOWN buttons.

• Press the DOWN button until reaching a stroke that allows the actuator to be hooked to the lever (point 4.5 - fig. 16 ref. A).

• Pressing the DOWN button opens the thruster until the limit switch is activated and the STATUS LED turns green (fig. 19 ref. B).

• The limit switch can be adjusted (point 4.8) if not in the right position (fig. 20A).

CONSTANT VELOCITY JOIN











WARNING: check that the CV joint is in a straight position, at an angle between -5° and $+5^{\circ}$ (Fig.20b)

• By pressing the UP button it is now possible to verify hatch closing and once the limit switch is reached, the STATUS LED turns red. If the stroke is not enough to reach the limit switch, adjust the latter during closing (point 4.8).



The retractable thruster is factory-set, so it should not be necessary to adjust it during closing.



EN . 4 - Installation

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• To adjust the FC1 and FC2 limit switches, slightly loosen the fixing screw and move them to the right or left as needed. Then tighten the fixing screw back (fig. 21B).



WARNING: during each adjustment of the FC1 and FC2 limit switches, check that the cam that operates them is always positioned between them and never over the required stroke.

- •Disconnect the retractable thruster from the power supply for at least five seconds (fig. 22). •Power the retractable thruster again (fig. 22).
- Enable a TCD control connected to the retractable thruster to open the hatch and make it operational (fig. 23).
- •Disable the previously enabled TCD control to close the retractable thruster (fig. 23).
- Make sure that the thermal cut-out has not tripped (the ERROR LED must be off see point 4.7 fig. 19/Ref. C).

4.9 - Installing spring end-of-stroke cables

• Open the hatch completely via the control (fig. 23).



WARNING: Once the hatch has been opened, turn off the power (fig. 22) to lock it in this position.

Fig. 24

Insert the two end-of-stroke cables into the appropriate seats.
Place the two cable stops, tension the two cables, making sure that both springs are tensioned at the same length, and tighten the cable stops with a 2.5mm Allen wrench.

Secure the cable stop by tightening the locknut with an 8 mm fork wrench, cut the excess cable with wire cutters leaving approx. 20mm beyond the cable stop.
Power the retractable thruster (fig. 22) which will

automatically close.

• To ensure correct operation, open the hatch a few times via the control (fig. 23).









5.0 - BTR basic system

Example of connection



* COMMON NEGATIVE FOR BATTERY GROUPS.

** WARNING: IN CASE OF OVERTEMPERATURE, THE THERMAL CUT-OUT ON THE MOTOR WILL TRIGGER AND INTERRUPT THE NEGATIVE CONTACT ON THE CONTACTOR. WAIT FOR THE TIME NEEDED FOR REACTIVATION.

EN 5 - Wiring diagram

5.1 - RTC R1 board





6.0 - Dip-Switch for option selection

SELECTION	FUNCTION	DIP-SWITCH
1	Reserved (always keep off)	
2	It indicates to the CAN control station that the thruster is in the bow (OFF)	ON 1 2 3 4
	It indicates to the CAN control station that the thruster is in the stern (ON)	ON 1 2 3 4
3	Reserved (always keep off)	ON 1 2 3 4
4 Reserved (always keep off)		ON 1 2 3 4
FACTORY SETTI	ON 1 2 3 4	

6.1 - Actuator current rotary selector

The ten selectable steps (from 0 to 9) allow you to set a percentage referring to the "maximum current/load" allowed for the actuator in use (see table).

ROTARY SELECTOR POSITION	MAXIMUM CURRENT/ LOAD %
0	28%
1	36%
2	44%
3	52%
4	60%
5	68%
6	76%
7	84%
8	92%
9	100%



If a setting other than the factory setting is required, proceed as follows:

1) With the board not powered, place the arrow of the rotary selector in the desired position.

2) After powering the board again, the percentage corresponding to the selected position will be automatically set.

If the maximum current/load limit is too low compared to the real needs of use, the thermal cut-outs of the actuator may be tripped during retractable thruster closing and opening with error 1 and 7 flashing.

7.0 - Light signals

Below is the meaning of the light signals provided by the RTC R1 board (see electronic board on page 13).

POWER LED (GREEN)

LED STATUS	DESCRIPTION
OFF	Board not powered
FLASHING SHORTLY	Board powered but control not enabled
FLASHING FAST	Board powered and active manual actuator movement mode
ON WITH SHORT SHUTDOWN	Board powered but control not enabled and link active with CAN control station
ON	Board powered and control enabled (TCD or CAN station).

LA STATUS LED (TWO-COLOUR)

LED COLOUR	LED STATUS	DESCRIPTION
-	OFF	With board powered, active manual actuator movement mode and limit switch fault present
RED	ON	Retractable unit closed (active LSC limit switch)
GREEN	ON	Retractable unit open (active LSO limit switch)
ORANGE	ON	Retractable unit neither open nor closed (LSC and LSO limit switches not active)
ORANGE	FLASHING	Retractable unit neither open nor closed (LSC and LSO limit switches not active) and linear actuator in motion.

ERROR LED (RED)

NUMBER OF FLASHES	DESCRIPTION
NONE	No fault detected.
1	High rising actuator absorption (retractable unit closing). The signal is triggered after the system has made three attempts to rise in the presence of mechanical friction above the set threshold. The problem can be caused by a foreign body entering the mechanism, the boat sailing at high speed, or mechanical problems with the retractable thruster and its hatch.
2	Fuse open. A current absorption greater than 10A has occurred. The problem may occur if there is a short circuit or overload on the actuator power line. Check the wiring of the power lines from the board to the actuator or the absorption of the actuator itself.
3	Abnormal limit switch condition. The problem is reported if the board detects a fault on the limit switches (both activated). Check the power line wiring from the board to the limit switches and their operation.
4	Actuator control line interruption. The problem is reported if the board detects an interruption in the actuator control power line. Check the wiring of the power lines from the board to the actuator.
5	Actuator movement timeout tripped. The problem is reported if the movement imparted to the actuator is not carried out within a period of 15 seconds.
6	Incorrect dip-switch configuration. The problem is reported if the dip-switch positions are not set correctly.
7	High lowering actuator absorption (retractable unit opening). The signal is triggered after the system has made three attempts to lower in the presence of a mechanical friction above the set threshold. The problem can be caused by a foreign body entering the mechanism, the boat sailing at high speed, or mechanical problems with the retractable thruster and its hatch.
8	High absorption of motor reversing contactor control output . The problem is reported if the board detects a short circuit or overload on the motor control power line. Check the wiring of the power lines from the board to the motor and the absorption of the reversing contactor/motor unit installed on the retractable thruster.
9	Motor thermal cut-out tripped. The problem is reported if the thermal cut-out of the motor has tripped. Wait for it to cool down.
7	Interruption of motor reversing contactor control output connection. The problem is reported if the board detects an interruption in the motor control power line. Check the wiring of the power lines from the board to the reversing contactor/motor unit installed on the retractable thruster.



8.0 - Important cautions



• This thruster is not designed for continuous use. It is equipped with protections which limit its operation at a maximum time span, as reported on the controls' manual. It is strongly forbidden to bypass or modify such protections in order to increase the operating time span, as these actions will void the warranty, thus lifting any responsibility from Quick® SPA.

• Make sure no swimmers or floating objects are in the vicinity before switching on the retractable thruster.

• In order not to damage the system, it is recommended to avoid navigating with the retractable thruster open and to open and close the thruster within a maximum speed of 4 knots and to proceed in reverse at a maximum speed of 2 knots, always taking into account the currents.

• In order not to damage the system, it is also recommended not to enable the thruster at speeds exceeding four knots.

• There must not be flammable materials in the peak or in the area where the Bow Thruster motor is.

• During mooring, it is recommended not to leave in the water any free line, which may be sucked in by the thrusters, thus leading them to break (fig. 24).





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9.0 - Retractable thruster use

To use the retractable thruster, refer to the TCD control manual

Start-up

When powered on, the RTC R1 board checks the position of the retractable thruster (raised, lowered, or in intermediate position). In the event that it is raised, the system does not perform actions.

In the event that it is lowered or in an intermediate position, it will control the rise of the retractable thruster.

Enabling control from TCD (Retractable thruster lowering)

When the RTC R1 board is enabled by a TCD control, the retractable thruster lowering procedure begins.

The right/left commands coming from the TCD will be inhibited until the procedure is completed.

During the lowering phase, the RTC R1 board measures the current drawn by the linear actuator.

If due to mechanical friction there is a high absorption of the linear actuator, the lowering will be reversed for a short time and then resumed. The RTC R1 board will report the problem after 3 attempts.

Disabling control from TCD (Retractable thruster rising)

When the RTC R1 board is disabled by a TCD control, the retractable thruster rising procedure begins.

On the way up, the right/left commands coming from the TCD will be inhibited.

During the rising phase, the RTC R1 board measures the current drawn by the linear actuator.

If due to mechanical friction there is a high absorption of the linear actuator, the rising will be reversed for a short time and then resumed. The RTC R1 board will report the problem after 3 attempts.

Automatic rising in case of TCD time-out

With the thruster down, the retractable thruster performs the rising procedure after 6 minutes from the last right or left command of the TCD.

Error detection from the TCD

If the TCD sends an error signal into the network (extended command, line interruption, short circuit on the right or left output), the retractable thruster performs the rising procedure.



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9.1 - Manual closing of the thruster in case of emergency

There is a slotted screw on the actuator, under the label (Ø185) or under the cover (Ø250/Ø300); turn it clockwise to close the system.





10 - Maintenance

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Fig. 26

Quick[®] Thrusters are made in materials that are resistant to the sea environment: in any case, it is indispensable to periodically remove salt deposits that form on the outer surfaces to avoid corrosions with consequent system inefficiency.



WARNING: make sure that the power supply to the electric motor is not switched on when maintenance operations are carried out.

DEPENDING ON USE, PERIODICALLY CHECK THE TIGHTNESS OF THE OIL SEALS AND REPLACE THEM IF NECESSARY.

Dismantle once a year, following the points below:

- Clean propellers, tunnel and gearleg.
- Replace the propellers if damaged or worn out.
- Replace the anodes (replace more frequently if necessary) and, if possible, lubricate the
- CV joint with marine grease (fig. 26).
- Check the tightness of all screws.
- Ensure that there is no water seepage inside.
- Check that all electrical connections are well tightened and oxide-less.
- Check that the batteries are in good conditions.
- Eliminate any graphite residues produced by the normal wear of the motor brushes.



WARNING: do not paint the anodes, the seals and the gearleg shafts where the thrusters are lodged.

11 - Product disposal

As with installation, at the end of this product life, dismantling must be carried out by qualified personnel.

This product is made up of various materials, some can be recycled and others must be suitably disposed of; enquire about the recycling or disposal systems provided for by local regulations for this product category.

Some parts of the product may contain pollutants or hazardous substances that, if dispersed, may be harmful to the environment and human health.



As indicated by the symbol on the side, it is forbidden to dispose of this product as domestic waste. Separate the products for disposal in accordance with the regulations in force in your area or return the product to the seller when purchasing a new equivalent product.

Local regulations may impose severe penalties for the improper disposal of this product.



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7 KEY

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14 SCREW

16

12 - List of components

BTR 140 Pag.24

NAME	15	RRC RX CONTAINER	31	PIN
SCREW	16	CABLE GLAND	32	ACTUATOR
GROWER	17	SCREW	33	PIN
MOTOR	18	WASHER	34	PIVOT
REVERSING CONTACTOR BOX	19	THREADED INSERT	35	OIL SEAL
WASHER	20	NUT	36	SNAP RING
SCREW	21	ANGLE BRACKET	37	BEARING
REVERSING CONTACTOR BOX	22	HINGE BRACKET	38	SHAFT
GUARD REVERSING CONTACTOR BOX	23	WASHER	39	SUPPORT
GUARD FASTENER	24	SCREW	40	CONSTANT
FLANGE	25	WASHER	41	SCREW
PIN	26	HINGE ARM	42	WASHER
SCREW	27	HATCH BRACKET	43	NUT
FIXING RING	28	HINGE SHAFT	44	OIL SEAL
OIL SEAL	29	ACTUATOR LEVER	45	OIL SEAL
O-RING	30	HINGE SHAFT	46	EXTERNAL S

35	OIL SEAL
36	SNAP RING
37	BEARING
38	SHAFT
39	SUPPORT
40	CONSTANT VELOCITY JOINT
41	SCREW
42	WASHER
43	NUT
44	OIL SEAL
45	OIL SEAL
46	EXTERNAL SNAP RING

HATCH BRACKET

SHAFT SUPPORT

EXTERNAL SNAP RING

EXTERNAL SNAP RING OIL SEAL

EXTERNAL SNAP RING

CONSTANT VELOCITY JOINT TILTING BODY

SHAFT SUPPORT

CONSTANT VELOCITY JOINT

INTERNAL SNAP RING

BEARING

OIL SEAL

ANODE SCREW

GROWER

OIL SEAL

WASHER

KEY INSERT GROWER

35

36

37

38

39

40

41 SPRING

42 43

44 SCREW

45

46

47

48

49 SCREW

50

51

49 NUT 50 O-RING

51

53

BEARING EXTERNAL SNAP RING

47	CYLINDER HEAD SCR
48	GROWER
49	KEY INSERT
50	TILTING BODY
51	ANODE
52	SCREW
53	SCREW
54	GROWER
55	SPRING
56	CABLE STOP
57	SCREW
58	NUT
59	BEARING
60	KEY
61	SHAFT
62	O-RING

PIVOT

SCREW

ANODE

SCREW

SCREW

SCREW

SPRING SHAFT

SCREW

53 BEARING

OIL SEAL

SHAFT

WASHER

SCREW

CABLE STOP SCREW

REDUCTION GEAR

THRUSTER 250 R THRUSTER 250 L

GROWER O-RING

CABLE STOP

NUT TILTING BODY

LEVER EXTERNAL SNAP RING

INTERNAL SNAP RING

EXTERNAL SNAP RING

55

56 57

58 59

60

61 62

63 PIN

64 NUT

65 LEVER

66

67

68

69

70

71

72

73

54

55

56

57

58

59 NUT

60

61

62 GASKET

63

64 KEY

65

66

67 ANODE

68

69

70 SCREW

RETRACTABLE THRUSTER TUNNEL ROPE GUIDE 63 64 65 WASHER 66 67 SCREW GEARBOX GASKET 68 69 70 71 72 73 74 REDUCTION GEAR SCREW SCREW NUT ANODE SCREW

SCREW 75 CABLE

- GASKET 74 75 76 KEY GEARLEG 77 78 79 80 81 82 PIN THRUSTER 185 R THRUSTER 185 L NUT ANODE SCREW TUNNEL ROPE GUIDE 83 84 85 WASHER 86 SCREW 87 SELF-LOCKING NUT 88 SELF-LOCKING NUT
- 89 CABLE
- WASHER 71 72 73 74 NUT NUT SCREW 75 76 77 ROPE GUIDE HINGE SHAFT HINGE BRACKET 78 79 WASHER HINGE ARM 80 HATCH BRACKET 81 SCREW 82 ANGLE BRACKET 83 WASHER SELF-LOCKING NUT 84 CABLE 85

74	SELF-LOCKING NUT
75	COUNTER FLANGE
76	WASHER
77	NUT
78	HINGE SHAFT
79	HINGE BRACKET
80	WASHER
81	HINGE ARM
82	HATCH BRACKET
83	SCREW
84	ANGLE BRACKET
85	WASHER
86	SELF-LOCKING NUT
87	KEY
88	ADAPTER
89	CABLE

BTR 185 Page 25

NO.	NAME	18	OIL SEAL	37	HATCH BR
1	SCREW	19	KEY	38	OIL SEAL
2	GROWER	20	ACTUATOR LEVER	39	INTERNAL
3	MOTOR	21	ACTUATOR PLATE	40	BEARING
4	REVERSING CONTACTOR BOX	22	CABLE GLAND	41	SHAFT
5	WASHER	23	SCREW	42	KEY
6	SCREW	24	RRC RX CONTAINER	43	WASHER
7	REVERSING CONTACTOR BOX	25	PIN	44A	BEARING
	GUARD	26	SPRING RING	44B	BEARING
8	REVERSING CONTACTOR BOX GUARD FASTENER (NUT)	27	ACTUATOR	45	SHAFT SUP
9	SCREW	28	SCREW	46	OIL SEAL
10	SCREW	29	PIVOT	47	EXTERNAL
11	FLANGE	30	PIN	48	PLATE
12	CHASSIS	31	ANGLE BRACKET	49	CONSTANT
13	SCREW	32	HINGE BRACKET	50	EXTERNAL
14	WASHER	33	HINGE SHAFT	51	OIL SEAL
15	NUT	34	SCREW	52	NUT
16	O-RING SEAL	35	WASHER	53	SHAFT
17	O-RING	36	HINGE ARM	54	SHAFT
RTI	2 250 Pag 26				

BTR 250 Pag.26

RING 13

PIN 15

BTR 300 Pag.27

Ν	NAME	17	WASHER
1	SCREW	18	SPRING RING
2	GROWER	19	RRC RX CONTAINER
3	MOTOR	20	CABLE GLAND
4	REVERSING CONTACTOR BOX	21	SCREW
5	REVERSING CONTACTOR BOX	22	WASHER
-	GUARD REVERSING CONTACTOR BOX	23	ACTUATOR BRACKET
6	GUARD FASTENER	24	PIN
7	SCREW	25	SCREW
8	FLANGE	26	ACTUATOR
9	CHASSIS	27	ACTUATOR PLATE
10	O-RING	28	NUT
11	OIL SEAL	29	OIL SEAL
12	RING	30	INTERNAL SNAP RING
13	SCREW	31	SHAFT
14	PIN	32	KEY
15	ACTUATOR LEVER	33	BEARING
16	PIN	34	EXTERNAL SNAP RING

NUT 52 O-RING SHAFT SUPPORT 35 36 OIL SEAL 37 CONSTANT VELOCITY JOINT TILTING BODY SPRING 38 39 40 ANODE 41 SCREW 42 STUD 43 44 GROWER OIL SEAL 45 KEY INSERT 46 GROWER 47 SCREW 48 WASHER

J	4	OIL JLAL
5	5	CABLE STOP
5	6	SCREW
5	7	NUT
5	8	SHAFT
5	9	TUNNEL
6	0	GASKET
6	1	REDUCTION GEAR
6	2	KEY
6	3	THRUSTER 250 R
6	4	THRUSTER 250 L
6	5	ANODE
6	6	SCREW
6	9	WASHER
7	0	SCREW
7	1	NUT
7	2	SCREW
7	3	ROPE GUIDE

54 OIL SEAL





EN 12 - List of components

12.0 - BTR 140





24

12.1 - BTR 185



EN (12 - List of components



12.3 - BTR 300



13 - Spare parts

EN

NO DESCRIPTION CODE 1 1A OSP CONSTANT VELOCITY JOINT Ø140 FVSGG140BTR0A00 OSP CONSTANT VELOCITY JOINT Ø185 1B FVSGG185BTR0A00 1C OSP CONSTANT VELOCITY JOINT Ø250 FVSGG250BTR0A00 OSP CONSTANT VELOCITY JOINT Ø300 1D FVSGG300BTR0A00 OSP DIAMOND CASING 'A' KIT FVSGCARBTOR1A00 2A FVSGCARBTQR1B00 2B OSP DIAMOND CASING 'B' KIT OSP HINGE + SUPP. BRACKET KIT BTR140 FVSGCN140000A00 ЗA 3B OSP HINGE + SUPP. BRACKET KIT BTR185 FVSGCN185000A00 2 3C OSP HINGE + SUPP. BRACKET KIT BTR250 FVSGCN250000A00 q 0 3D OSP HINGE + SUPP. BRACKET KIT BTR300 FVSGCN30000A00 0 4A OSP MOTOR 1500W 12V BTR 140+T FVEMFEL1512B14T 4B OSP MOTOR 2200W 12V BTR 140+T FVEMFEL2212B14T 4C OSP MOTOR 3300W12V BTR185+T FVEMFEL3312B18T 4D OSP MOTOR 3300W24V BTR185+T FVEMFEL3324B18T 4E OSP MOTOR 4300W12V BTR185+T FVEMFEL4312B18T -4F OSP MOTOR 4300W24V BTR185+T FVEMFEL4324B18T 3 **°**0 d 4G OSP MOTOR 6300W12V BTR185+T FVEMFEL6312B18T 4H OSP MOTOR 6300W24V BTR185+T FVEMFEL6324B18T 41 OSP MOTOR 6500W 24V BTR250+T EVEMFEL6524B25T OSP MOTOR 8000W 24V BTR250+T FVEMFEL8024B25T 4J OSP MOTOR 10KW 24V BTR250+T FVEMFEL1K24B25T 4K OSP MOTOR 10KW 24V BTR300+T FVEMFEL1K24B30T 4L OSP MOTOR 12KW 24V BTR300+T FVEMFEL2K24B30T 4M 4N OSP MOTOR 15KW 48V BTR300+T FVEMFEL5K48B30T OSP COMP. STAINLESS STEEL WIRE ROPE KIT BTR140 FVSFBTR14000A00 5A 5B OSP COMP. STAINLESS STEEL WIRE ROPE KIT BTR185 FVSFBTR18500A00 4 5C OSP COMP. STAINLESS STEEL WIRE ROPE KIT BTR250 FVSFBTR25000A00 OSP COMP. STAINLESS STEEL WIRE ROPE KIT BTR300 FVSFBTR30000A00 9 5D OSP REV. CONTACTOR BOX KIT 150A 12V 6A FVSGRCT15012A00 6B OSP REV. CONTACTOR BOX KIT 150A 24V FVSGRCT15024A00 (3) 6C OSP REV. CONTACTOR BOX KIT 350A 12V FVSGRCT35012A00 6D OSP REV. CONTACTOR BOX KIT 350A 24V FVSGRCT35024A00 7 OSP THERMAL CUT-OUT KIT FVKPS120BTR0A00 8A OSP ACTUATOR 12V Ø140 FVEAL1401200000 8B OSP ACTUATOR 12V Ø185 EVEAI 1851200000 ۲ 8C. OSP ACTUATOR 24V Ø185 EVEAI 1852400000 8D OSP ACTUATOR 24V Ø250 FVEAL2502400000 8E OSP ACTUATOR 24V Ø300 FVEAL3002400000 8F OSP ACTUATOR 48V Ø300 FVEAL3004800000 **OSP FLANGE KIT BTR140** FVEFGMBTR140000 9A 9B **OSP FLANGE KIT BTR185** FVEFGMBTR185000 0000 5 9C OSP FLANGE KIT BTR250D00 FVEFGMBTR250000 9D **OSP FLANGE KIT BTR300** FVEFGMBTR300000 10A **OSP ANODES FOR PROPELLER KIT BTR185** FVSGANBTR18AA00 OSP ANODES FOR PROPELLER KIT BTR250E00 10B FVSGANBTR25EA00 10C OSP ANODES FOR PROPELLER KIT BTR300 FVSGANBTR30AA00 11C OSP ANODES FOR PROPELLER KIT BTR140 FVSGANBTR14AA00 12A OSP PROPELLER D185 LH OUICK 5 BLADES BLACK FVSGEL185L05A00 12B OSP BTR THRUSTER D250 LH QUICK 5 BLADES E00 FVSGEL250LE5A00 13A OSP THRUSTER D185 RH OUICK 5 BLADES FVSGEL185R05A00 6 13B OSP THRUSTER D250 RH OUICK 5 BLADES F00 EVSGEL250RE5A00 13C. OSP THRUSTER KIT BTR 140 RH 5 BLADES EVSGEI 140R00A00 OSP THRUSTER KIT LH BTR 300 14 FVSGEL300L00A00 OSP THRUSTER KIT RH BTR 300 FVSGEL300R00A00 15 **OSP GEARBOX KIT BTO140** FVSGGBBT1400A00 16 17A OSP GEARBOX KIT BTO185 DP FVSGGBBT185DA00 17B OSP GEARBOX KIT BTR250 E00 FVSGGBBTR25EA00 7 17C OSP GEARBOX KIT BTQ 300 FVSGGBBT3000A00 18A OSP HINGE VERT. FIX. ANGLE BRACKET BTR140 FVSLPVNG1400A00 18B OSP HINGE VERT. FIX. ANGLE BRACKET BTR185 FVSLPVNG1850A00 18C OSP HINGE VERT. FIX. ANGLE BRACKET BTR250 FVSLPVNG2500A00

FVSLPVNG3000A00



18D OSP HINGE VERT, FIX, ANGLE BRACKET BTR300



14 - Dimensions

BTR 140



EN



generic image

14 - Dimensions

BTR 185 Pag.30

MOD.	BTR1856512	BTR1856524	BTR1858512	BTR1858524	BTR18510512	BTR18510524
Α	722 (28'	' 27/64)	743 (29" 1/4)	709 (27" 29/32)	801 (31" 17/32)	779 (30" 21/32)
В	300 (11'	' 13/16)	323 (12" 23/32)	287 (11" 5/16)	384 (15" 1/8)	361 (14" 7/32)
С	370 (14" 9/16)					
D	599 (23" 37/16)					
Е	300 (11" 13/16)					
F	150 (5" 29/32)					
G	94 (3" 45/64)					
Н	60 (2" 23/64)					

BTR 250 Pag.30

MOD.	BTR25012024	BTR25014024	BTR25024024		
Α	879 (34	" 39/64)	908 (35" 3/4)		
В	450 (17	515 (20" 9/32)			
С	394 (15 33/64) with actuator: 411 (16 3/16)				
D	754 (29″ 11/16)				
Е	406 (15" 63/64)				
F	200 (7" 7/8)				
G	154.5 (6″ 5/64)				
Н	63.5 (2" 1/2)				

BTR 300 Pag.30

MOD.	BTR30025024	BTR30027024	BTR30030048		
Α	954 (37" 9/16) 975 (38"3/8) 997 (39" 1/4)				
В	462 (18" 3/16) 514 (20" 1/4) 553 (21" 3/4)				
С	570 (22" 7/16)				
D	859 (33" 13/16)				
E	475 (18" 11/16)				
F	200 (7" 7/8)				
G	149 (5" 7/8)				
Н	114 (4" 1/2)				



BTR Series



January, 2023

BTR 18585 - 185105

BTR 250150 - 250220

BTR 300240 - 300300 - 300400

Product serial number



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